

# Differentiability with Respect to Lag Function for Nonlinear Pantograph Equations

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Differentiability with respect to  $\lambda \in (0, 1)$  is provided for the nonlinear pantograph equations  $y'(t) = f(t, y(t), y(\lambda t))$  via the fibre contraction theorem and Picard operators' technique.

## 1 Introduction

The subject matter of this paper is the  $\lambda$ -dependence of the solution of the initial value problems:

$$\begin{cases} y'(t) = f(t, y(t), y(\lambda t)), & t > 0 \\ x(0) = 0. \end{cases} \quad (1)$$

Occurring in number theory the linear version of (1), called the pantograph equation (PE), was first studied by Kato and McLeod in [9]. As well as the delay differential equations (DDE)  $y'(t) = f(t, y(t), y(t - \tau))$ , the PE belong to the class of functional differential equations (FDE). Differentiability with initial data for the FDE was first established by Hale in [1], but differentiability with respect to delays for DDE was proved relatively late by Hale and Ladeira in [2] using a generalized uniform contraction principle for quasi-Banach spaces. Also the soon to appear paper of Hokkanen and Moroşanu [4] gives a simple proof for DDE case. Neither of the methods cited above works on our problem. However the method presented by the author in [3] for DDE works out for PE too.

The Picard operators' technique proposed by Rus [5], [6] was first used on PE by V. Mureşan [10] in proving continuity with respect to  $\lambda$ .

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**Definition 1** Let  $(X, \tau)$  be a topological space and  $T : X \rightarrow X$  be a mapping.  $T$  is called Picard if the fixed point set of  $T$  namely  $F_T = \{x^*\}$  and  $T^n x_0 \rightarrow x^*$  whichever the starting point  $x_0 \in X$ .

Unfortunately by itself this method is not sufficient. The additional tool used is the fibre contraction theorem below [7], [8].

**Theorem 1** (Fibre Contraction Theorem) Let  $(X, d)$  be a metric space,  $(Y, \rho)$  be a complete metric space and  $T : X \times Y \rightarrow X \times Y$ . Suppose that

$$(i) T(x, y) = (T_1(x), T_2(x, y));$$

$$(ii) T_1 : X \rightarrow X \text{ is Picard};$$

$$(iii) \exists \lambda \in (0, 1) \text{ s. t. } \rho(T_2(x, y), T_2(x, z)) \leq \lambda \rho(y, z), \forall x \in X, y, z \in Y.$$

Then  $T$  is Picard.

The Picard operators' technique consist in considering the unique solution  $y^* = y^*(t, \lambda)$  of (1) as the unique fixed point of the operator

$$T_1 y(t, \lambda) = \int_0^t f(s, y(s, \lambda), y(\lambda s, \lambda)) ds. \quad (2)$$

Let  $y_n = T_1^n y_0$  be the  $n^{\text{th}}$ -iteration. In appropriate metric spaces we shall prove

$$y_n \rightarrow y^*$$

and

$$\frac{\partial y_n}{\partial \lambda} \rightarrow v^*.$$

Using an Weierstrass type argument we get  $v^*$  is differentiable with respect to  $\lambda$  and

$$v^* = \frac{\partial y^*}{\partial \lambda}.$$

## 2 Differentiability with respect to $\lambda$

Throughout this paper we assume that  $f \in C[0, \alpha] \times \mathbf{R}^{2n}, \mathbf{R}^n)$  and

$$f(t, \cdot, \cdot) \in C^1(\mathbf{R}^{2n}, \mathbf{R}^n) \forall t \in [0, \alpha]$$

and

$$\frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \in C([0, \alpha] \times \mathbf{R}^{2n}, \mathbf{R}^n).$$

In particular for

$$f \in C^1([0, \alpha] \times \mathbf{R}^{2n}, \mathbf{R}^n) \quad (3)$$

all the above hold.

Consider

$$X = \{y \in BC([0, \alpha] \times (0, 1), \mathbf{R}^n) : y(0, \lambda) = 0, y(\cdot, \lambda) \in C^1[0, \alpha] \forall \lambda \in (0, 1)\}$$

endowed with

$$\|y\|_{B_1} = \sup_{(t, \lambda) \in [0, \alpha] \times (0, 1)} |y(t, \lambda)| e^{-\mu t}$$

and

$$Y = BC([0, \alpha] \times (0, 1), \mathbf{R}^n)$$

with a similar norm

$$\|v\|_{B_2} = \sup_{(t, \lambda) \in [0, \alpha] \times (0, 1)} |y(t, \lambda)| e^{-\nu t}$$

for some  $\mu$  and  $\nu$  to be specified later on.

**Lemma 1**  $T_1 : (X, \|\cdot\|_{B_1}) \longrightarrow (X, \|\cdot\|_{B_1})$  given by (2) is a contraction for  $\mu$  large enough whence  $T_1$  is a Picard operator.

*Proof:* Using the Lipschitz condition of  $f(t, \cdot, \cdot)$  with a Lipschitz constant  $L$  independent of  $t \in [0, \alpha]$  we have

$$\begin{aligned} |T_1 y(t, \lambda) - T_1 z(t, \lambda)| &\leq L \int_0^t |y(s, \lambda) - z(s, \lambda)| e^{-\mu s} e^{\mu s} ds + \\ &\int_0^t |y(\lambda s, \lambda) - z(\lambda s, \lambda)| e^{-\mu \lambda s} e^{\mu \lambda s} ds \leq \frac{2L}{\mu} \|y - z\|_{B_1} e^{\mu t} \end{aligned}$$

whence

$$\|T_1 y - T_1 z\|_{B_1} \leq \frac{2L}{\mu} \|y - z\|_{B_1}$$

and choose  $\mu > 2L$ . ■

Consider now  $B_R \subset X$  a closed ball of radius  $R$ . For  $\alpha$  sufficiently small using the continuity of  $f$  we have  $B_R$  is invariant for  $T_1$  i.e.  $T_1(B_R) \subset B_R$ .

In the sequel we consider such an  $\alpha$  that  $B_R$  is invariant.  
 Consider now  $T_2 : X \times Y \longrightarrow Y$  defined by

$$\begin{aligned} T_2(y, v)(t, \lambda) &= \int_0^t \frac{\partial f}{\partial y}(s, y(s, \lambda), y(\lambda s, \lambda))v(s, \lambda)ds + \\ &+ \int_0^t \frac{\partial f}{\partial z}(s, y(s, \lambda s), y(\lambda s, \lambda))\frac{\partial y}{\partial s}(\lambda s, \lambda)sds + \\ &+ \int_0^t \frac{\partial f}{\partial z}(s, y(s, \lambda s), y(\lambda s, \lambda))v(\lambda s, \lambda)ds. \end{aligned}$$

It is clear that  $T_2$  is linear in  $v$  and is easy to see that  $T_2 : B_R \times Y \longrightarrow Y$  is a contraction in the  $v$ -variable with respect the  $\|\cdot\|_{B_2}$ - norm with a Lipschitz constant independent on  $x \in B_R$ .

Using the above facts and applying the fibre contraction theorem we are lead to the following

**Lemma 2**  $T : B_R \times Y \longrightarrow B_R \times Y$  defined by  $T = (T_1, T_2)$  is a Picard operator.

We are now ready to state and prove our main result.

**Theorem 2** Let  $f \in C^1([0, h] \times \mathbf{R}^{2n}, \mathbf{R}^n)$  then the unique solution of (1) is differentiable with respect to  $\lambda$ .

*Proof:* For the beginning we work with  $T \in [0, \alpha]$ .

Let  $(y^*, v^*)$  be the unique fixed point of  $T$  as given by Lemma 2. In particular  $y^*$  is the unique fixed point of  $T_1$  hence the solution of (1). Consider now  $y_0 = 0$  and  $v_0 = 0$  then

$$y_1(t, \lambda) = T_1 0(t, \lambda) = \int_0^t f(s, 0, 0)ds$$

is independent on  $\lambda$  whence

$$\frac{\partial y_1}{\partial \lambda}(t, \lambda) = 0.$$

But also  $v_1(t, \lambda) = T_2(0, 0)(t, \lambda) = 0$ .

Inductively, suppose that  $y_n$  is differentiable in  $\lambda$  and

$$\frac{\partial y_n}{\partial \lambda}(t, \lambda) = v_n(t, \lambda), \quad \forall t \in [0, \alpha], \quad \lambda \in (0, 1).$$

We have by the induction hypothesis

$$\begin{aligned} y_{n+1} &= T_1 y_n \\ v_{n+1} &= T_2(y_n, v_n) = T_2(y_n, \frac{\partial y_n}{\partial \lambda}) \end{aligned} \quad (4)$$

But

$$\begin{aligned} T_2(y_n, \frac{\partial y_n}{\partial \lambda})(t, \lambda) &= \int_0^t \frac{\partial f}{\partial y}(s, y(s, \lambda), y(\lambda s, \lambda)) \frac{\partial y_n}{\partial \lambda}(s, \lambda) ds + \\ &+ \int_0^t \frac{\partial f}{\partial z}(s, y(s, \lambda s), y(\lambda s, \lambda)) \frac{\partial y_n}{\partial s}(\lambda s, \lambda) s ds + \\ &+ \int_0^t \frac{\partial f}{\partial z}(s, y(s, \lambda s), y(\lambda s, \lambda)) \frac{\partial y_n}{\partial \lambda}(\lambda s, \lambda) ds. \end{aligned}$$

It's a simple computation that

$$T_2(y_n, \frac{\partial y_n}{\partial \lambda})(t, \lambda) = \frac{\partial T_1 y_n}{\partial \lambda}(t, \lambda) = \frac{\partial y_{n+1}}{\partial \lambda}(t, \lambda)$$

Therefore

$$\frac{\partial y_n}{\partial \lambda} = v_n, \quad \forall n \in \mathbf{N}.$$

So far we got a sequence  $(y_n)$  in  $X$  such that

$$y_n \xrightarrow{\|\cdot\|_{B_1}} y^*$$

and

$$\frac{\partial y_n}{\partial \lambda} \xrightarrow{\|\cdot\|_{B_2}} y^*.$$

Using a Weierstrass argument we conclude  $v^*$  is differentiable and

$$v^* = \frac{\partial y_n}{\partial \lambda}.$$

In order to consider the solution extended on larger  $t$  note for  $t \in [\alpha, \frac{\alpha}{\lambda}]$  we have  $\lambda t \in [\lambda\alpha, \alpha]$  where we already know the solution is differentiable in  $\lambda$ . Also we know that differentiability with respect to parameters for the solutions of ODE holds.

Assuming differentiability for solutions defined on  $I_n = [0, \frac{\alpha}{\lambda^n}]$  we prove it for solutions defined on  $I_{n+1} = [0, \frac{\alpha}{\lambda^{n+1}}]$ .

Let  $\psi$  be the solution of (1) restricted to  $I_n$  i.e.

$$\psi(t) = y^*(t), \quad \forall t \in I_n$$

For  $t \in I_{n+1}$  we have  $y^*$  satisfies the following ODE

$$y'(t) = f(t, y(t), \psi(\lambda t))$$

Remains to remark that the application

$$(t, \lambda) \in I_n \times (0, 1) \longrightarrow \psi(\lambda t)$$

is differentiable. Applying now the classical result for ODE we got differentiability for  $I_{n+1}$ . ■

### 3 Remarks

(i) The existence result and continuity with respect to  $\lambda$  result are hidden in our proof in the convergence

$$y_n \xrightarrow{\|\cdot\|_{B_1}} y^*$$

and do not require any small  $\alpha$  so that the result apply on the whole interval  $[0, h]$ .

(ii) For the linear case studied by Kato and McLeod [9]

$$y'(t) = ay(t) + by(\lambda t)$$

we have

$$\frac{\partial f}{\partial y}(t, y, z) \text{ and } \frac{\partial f}{\partial y}(t, y, z)$$

are bounded on the whole  $[0, h] \times \mathbf{R}^{2n}$  whence we can work with the operator  $T_1$  defined on the entire space  $X$  rather than on a closed ball and so we can also drop the assumption of  $\alpha$  small enough from the very beginning.

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